

TITLE OF THE INVENTION

STEP MOTOR

BACKGROUND OF THE INVENTION

5 1. Field of the Invention

This invention generally relates to small-sized step motors for use in cameras or the like, and more particularly, to a step motor suitable for use in driving a shutter, lens, barrier, and the like of a camera.

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2. Description of the Related Art

In recent years, cameras have become electronics devices and shutters thereof are driven by the step motors. In addition, cameras are promoted to be small-sized and light-weighted, leading to a demand for small-sized step motors with high accuracy. For example, Japanese Examined Patent Publication No. 2-2382 discloses a step motor that simultaneously excites two coils provided on a stator element (stator) and rotates a rotating element (rotor).

20 FIG. 7 is a plan view schematically showing a step motor 100 disclosed in Japanese Examined Patent Publication No. 2-2382. A stator 103 having a shape of isosceles trapezoid is provided in an outer periphery of a rotor 101. The stator 103 includes three magnetic poles 104, 105, and 106, and also includes a first coil 108 on the left and a second coil 109 on the right. The rotor 101 composed of a permanent magnet is rotated by controlling the direction of the current applied to the coils 108 and 109 to change the direction of the magnetic field. In addition, the third magnetic pole 106 is magnetically excited by left and right coils, and in particular, the third magnetic pole 106 includes a protrusion portion 107 that comes close to the rotor 101. The protrusion portion 107 is provided so that a North magnetic pole (or South magnetic pole) of the rotor 101 is positioned to the protrusion portion 107

when no magnetic field is set up.

It is preferable, however, that the step motor be designed to start the rotation from a halting state with less power consumption. However, the rotor 101 of 5 the above-mentioned step motor 100 has two magnetic poles, and it is configured that South magnetic pole or North magnetic pole is positioned to the protrusion portion 107 in a halting state. Therefore, the above-described step motor 100 has a drawback that a large 10 amount of energy is consumed at the time of starting the rotation.

SUMMARY OF THE INVENTION

It is an object of the present invention to solve 15 the above-mentioned drawback and provide a step motor in which the power consumption can be suppressed at the time of starting rotation of the rotor.

According to another aspect of the present invention, there is provided a step motor including a 20 rotor having four magnetic poles; a first magnetic pole magnetically excited by a first coil; a second magnetic pole magnetically excited by a second coil; and a third magnetic pole magnetically excited by the first coil and the second coil. A gap between the third magnetic 25 pole and the rotor is smaller than that between the first magnetic pole and the rotor and that between the second magnetic pole and the rotor. According to the present invention, the gap between the third magnetic pole and the rotor is smaller than that between the first magnetic pole and the rotor and that between the second magnetic pole and the rotor. By employing such 30 configuration, the effect of the magnetic field can be intensified from the third magnetic pole to the rotor having four magnetic poles. Accordingly, it is 35 possible to relatively weaken the magnetic fields set up from the first magnetic pole and the second magnetic pole, which tend to intensify the influence on the

5 rotor, enabling the power consumption to be reduced at the time of starting the rotation of the rotor. Thus, it is possible to provide the step motor, which can save energy and consume less power and generate a high drive torque at the time of starting the rotation.

BRIEF DESCRIPTION OF THE DRAWINGS

10 Preferred embodiments of the present invention will be described in detail with reference to the following drawings, wherein:

FIG. 1 is a view showing main components of a step motor in accordance with an embodiment;

15 FIGs. 2A through 2E are views showing a case where a rotor of the step motor is rotated in a two-phase magnetically excited state in accordance with an embodiment;

20 FIGs. 3A through 3E are views showing a case where a rotor of the step motor is rotated in a clockwise direction in a one-phase magnetically excited state in accordance with an embodiment;

FIGs. 4A through 4E are views showing a case where a rotor of the step motor is rotated in a counterclockwise direction in a one-phase magnetically excited state in accordance with an embodiment;

25 FIG. 5 is a view showing a stator having a preferred shape suitable for use in the step motor;

FIG. 6 is a perspective view showing an appearance of a module having a structure of the step motor; and

30 FIG. 7 schematically shows a conventional step motor.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

35 A description will now be given, with reference to the accompanying drawings, of an embodiment of the present invention. FIG. 1 is a view showing main components of a step motor in accordance with an

embodiment of the present invention. A step motor 1 includes a rotor 2 and a stator 3, the rotor 2 being arranged in the center thereof and capable of rotating in both directions, the stator 3 being arranged to face an outer circumference of the rotor 2. The rotor 2 has a cross-section of circle and has a shape of cylinder. The stator 3 is integrally formed to have a plan view of substantially lateral U-shape, and is located in a state that the rotor 2 is housed in an internal space thereof. In addition, the step motor 1 is shown in FIG. 1 with an open end of the lateral U-shape facing upwardly.

The rotor 2 includes four magnetic poles, which are composed of two North magnetic poles and two South magnetic poles. The rotor 2 is a permanent magnet magnetized in positions where the poles having a same polarity face each other, and is rotatably provided in both directions around an axis 21. Both ends of the stator 3 having the above-mentioned lateral U-shape are formed to face a circumferential surface of the rotor 2. The both ends are respectively a first magnetic pole 11 and a second magnetic pole 12. Also, a third magnetic pole 13 is arranged in an intermediate position of the first magnetic pole 11 and the second magnetic pole 12.

A first coil 4 is wound between the first magnetic pole 11 and the third magnetic pole 13, and a second coil 5 is wound between the second magnetic pole 12 and the third magnetic pole 13. The first magnetic pole 11 is magnetically excited when a current flows through the first coil 4, and the second magnetic pole 12 is magnetically excited when a current flows through the second coil 5. In contrast, the third magnetic pole 13 is magnetically excited by both the first coil 4 and the second coil 5. Accordingly, a magnetically excited state of the third magnetic pole 13 is shown as a combination of current-flowing states of the first

coil 4 and the second coil 5.

FIG. 1 shows a current control circuit 25, which is indicated as a dotted line and connected to the first coil 4 and the second coil 5 of the step motor 1. 5 In accordance with the present embodiment, the current control circuit 25 supplies the current to magnetically excite the first coil 4 and the second coil 5. Such supplied current includes two patterns that have been set. In a first pattern, the current is supplied from 10 the current control circuit 25 to magnetically excite both the first coil 4 and the second coil 5, and a drive state of the rotor 2 is controlled by changing a current supply direction in each coil. In the first pattern, there are two state: one state is that the 15 first magnetic pole 11 and the second magnetic pole 12 are magnetically excited to have a same magnetic polarity and the other state is that the first magnetic pole 11 and the second magnetic pole 12 are magnetically excited to respectively have different 20 types of magnetic polarity. At this time, if the first magnetic pole 11 and the second magnetic pole 12 are magnetically excited to have the same magnetic polarity, which results in that the third magnetic pole 13 sets up a stronger magnetic field than those of the 25 afore-mentioned magnetic poles. On the contrary, if the first magnetic pole 11 and the second magnetic pole 12 are magnetically excited to respectively have different types of magnetic polarity, magnetization in the third magnetic pole 13 is cancelled each other, 30 resulting in a non-magnetization state.

In a second pattern, the current is supplied from the current control circuit 25 to magnetically excite either the first coil 4 or the second coil 5, and the drive state of the rotor 2 is controlled by changing 35 the current supply direction. In the second pattern, only either the first magnetic pole 11 or the second magnetic pole 12 is magnetically excited, and it is

changed to have an opposite magnetic polarity by changing the current supply direction. In the second pattern, the third magnetic pole 13 is magnetically excited to have an opposite polarity of those of the 5 first magnetic pole 11 and the second magnetic pole 12 that has been magnetically excited.

In the first pattern, the drive of the rotor 2 is controlled by a two-phase magnetically excited state in which the first coil 4 and the second coil 5 are 10 magnetically excited. On the other hand, in the second pattern, the drive of the rotor 2 is controlled by a one-phase magnetically excited state in which only either of the first coil 4 or the second coil 5 is magnetically excited. A description will be given 15 later in detail, with reference to the drawings, of rotation states of the rotor 2 in the first pattern and in the second pattern.

In the step motor 1, the rotor 2 is configured to include four magnetic poles, and in particular, is 20 configured to be capable of reducing the torque. This point will now be described. In the step motor 1, a same gap d is configured to be a distance between the circumferential surface of the rotor 2 and the first magnetic pole 11 and a distance between the 25 circumferential surface of the rotor 2 and the second magnetic pole 12. In contrast, a gap D is a distance between the circumferential surface of the rotor 2 and the third magnetic pole 13, and is configured to be smaller than the gap d . The gap D is configured to be 30 narrow so as to intensify the magnetic field set up from the third magnetic pole 13 to work on the rotor 2 and relatively weaken the magnetic field set up from the first magnetic pole 11 and that set up from the second magnetic pole 12 to work on the rotor 2. 35 Preferably, the gap D is configured to be approximately 0.3 to 1 times as long as the gap d . More preferably, approximately 0.8 times.

If the magnetic fields set up from the first magnetic pole 11 and the second magnetic pole 12 intensely work on the rotor 2, this increases detent torque of the rotor 2 in the halting state.

5 Accordingly, in the step motor 1, the gap D between the circumferential surface of the rotor 2 and the third magnetic pole 13 is configured to be small and intensify the influence of the third magnetic pole 13, so as to relatively decrease the magnetic influence

10 produced from the first magnetic pole 11 and the second magnetic pole 12 that work on the rotor 2. Thus, the detent torque is decreased by averaging the magnetic balance between the stator 3 and the rotor 2. This makes it possible to reduce the power consumption in

15 the step motor 1. The conventional step motor as described above is also configured in such a manner that the third magnetic pole is arranged close to the rotor. The rotor in the aforementioned step motor includes two magnetic poles, and a third magnetic pole

20 is arranged close to the rotor so that one of the magnetic poles in the rotor stops to face the third magnetic pole. However, in the step motor 1 in accordance with an embodiment, the third magnetic pole 13 is arranged close to the surface of the rotor 2 so

25 that the magnetic fields set up from the respective magnetic poles to work on the rotor 2 are balanced to reduce the torque. In this manner, different effects are obtainable with seemingly similar configurations. This is because the step motor 1 in accordance with an

30 embodiment of the present invention employs the rotor 2 having four magnetic poles.

Hereinafter, a description will be given of, with reference to FIG. 2A through FIG. 4E, the rotation of the rotor 2 in the step motor 1. FIGs. 2A through 2E show the above-described first current supply pattern, and the rotor 2 is rotated by the two-phase magnetically excited state that excites the first coil

4 and the second coil 5. FIG. 3A through FIG. 4E show the above-described second pattern, and the rotor 2 is rotated by a one-phase magnetically excited state that excites only either the first coil 4 or the second coil 5. In particular, FIGs. 3A through 3E show a case where the first coil 4 is magnetically excited, and FIGs. 4A through 4E show a case where the first coil 4 is magnetically excited. The current is supplied to the coils 4 and 5 shown in FIG. 2A through FIG. 4E by the current control circuit 25 shown in FIG. 1, yet it is not shown in these drawings. In addition, FIG. 3A through FIG. 4E show only coils through which the current is flown to facilitate the understanding.

Referring to FIGs. 2A through 2E, a description will be given of how the rotor 2 of the step motor 1 rotates. FIGs. 2A through 2E show the above-mentioned first pattern, and also show a case where the first coil 4 and the second coil 5 are magnetically excited to rotate the rotor 2 in a clockwise direction (in a right-hand direction) at a step angle of 45°. In FIG. 2A, there is no current flowing through the coils 4 and 5. In FIG. 2B through FIG. 2E, the current is controlled to supply to the coils 4 and 5 and rotate the rotor 2 in a clockwise direction in a time-series manner. In FIG. 2A, the first magnetic pole 11 and the second magnetic pole 12 are not magnetically excited, and South magnetic pole and North magnetic pole of the rotor 2 are respectively arranged to face the first magnetic pole 11 and the second magnetic pole 12.

In FIG. 2B, the current flows through the first coil 4 and the second coil 5 from the state shown in FIG. 2A, and both the first magnetic pole 11 and the second magnetic pole 12 are magnetically excited to be South magnetic pole. At this time, the magnitude of North magnetic pole is doubled and excited in the third magnetic pole 13. Next, in FIG. 2C, the excitation state in the first magnetic pole 11 is retained in

South magnetic pole from the state shown in FIG. 2B, and the second magnetic pole 12 is magnetically excited to be reversed to North magnetic pole. At this time, North magnetic pole and South magnetic pole are 5 magnetically excited and cancelled each other, resulting in no magnetization in the third magnetic pole 13. In the same manner, in FIG. 2D, the first magnetic pole 11 and the second magnetic pole 12 are both magnetically excited to be North magnetic pole 10 from the state shown in FIG. 2C. At this time, the magnitude of North magnetic pole is doubled and excited in the third magnetic pole 13. Next, in FIG. 2E, the excitation state in the first magnetic pole 11 is retained in North magnetic pole from the state shown in 15 FIG. 2D, and the second magnetic pole 12 is magnetically excited to be opposite, namely, to be South magnetic pole. At this time, North magnetic pole and South magnetic pole are magnetically excited and cancelled each other, resulting in no magnetization in 20 the third magnetic pole 13.

As described, the rotor 2 is rotated in a clockwise direction in steps of 45° as shown in the drawings, as the magnetization state gradually changes in the magnetic poles 11 through 13 in the stator 3. 25 Here, the respective drawings of FIGs. 2A through 2E show that the current flows through the first coil 4 and the second coil 5 and the rotor 2 is located in a position where a rotation of 45° is completed. As shown in FIG. 2B, when the coils 4 and 5 are 30 magnetically excited by the current supplied from the current control circuit 25 and changed from the halting state of the rotor 2 shown in FIG. 2A, the torque is applied to the rotor 2 in a clockwise direction. When the rotor 2 starts rotating in a clockwise direction, 35 the step motor 1 is capable of starting the rotation with relatively less power consumption, because the third magnetic pole 13 is arranged close to the surface

of the rotor 2. That is to say, a current amount supplied from the current control circuit can be reduced, enabling the rotor 2 to be rotated for purposes of saving energy.

5 FIGs. 3A through 3E show the above-mentioned second current supply pattern, and also show a case where only the first coil 4 is magnetically excited in a one-phase magnetically excited state to rotate the rotor 2 in a clockwise direction (in a right-hand 10 direction) at a step angle of 90°. In FIG. 3A, there are no currents flowing across the coils 4 and 5. In FIG. 3B through FIG. 3E, the current is controlled to supply to the coil 4 to rotate the rotor 2 in a clockwise direction in steps of 90° in a time-series 15 manner. In FIGs. 3A through 3E, a polarity of the first magnetic pole 11 is reversed by reversing the current direction supplied to the first coil 4. At this time, the polarity of the third magnetic pole 13 is an opposite one of the first magnetic pole. In 20 addition, the second magnetic pole 12 is not magnetically excited from the coil, and has the same polarity as that of the third magnetic pole 13.

First, in FIG. 3A, the first magnetic pole 11 and the second magnetic pole 12 are not magnetically 25 excited, and South magnetic pole and North magnetic pole of the rotor 2 are respectively arranged to face the first magnetic pole 11 and the second magnetic pole 12, same as shown in FIG. 2A. In FIG. 3B, next, the current flows across the first coil 4 from the state of 30 FIG. 3A, and the first magnetic pole 11 is magnetically excited to be South magnetic pole. At this time, the third magnetic pole 13 and the second magnetic pole 12 are magnetically excited to be North magnetic pole. In FIG. 3C, which is subsequently shown, the first 35 magnetic pole 11 is changed to be North magnetic pole in the magnetically excited state from the state shown in FIG. 3B, and the third magnetic pole 13 and the

second magnetic pole 12 are magnetically excited to be reversed to South magnetic poles. In the same manner, in FIG. 3D, the first magnetic pole 11 is magnetically excited to be South magnetic pole from the state shown 5 in FIG. 3C. At this time, the third magnetic pole 13 and the second magnetic pole 12 are magnetically excited to be North magnetic poles. In FIG. 3E, next, the first magnetic pole 11 is changed to be North magnetic pole from the state shown in FIG. 3D, and the 10 third magnetic pole 13 and the second magnetic pole 12 are magnetically excited to be opposite, namely, to be South magnetic pole.

As described above, the rotor 2 is rotated in a clockwise direction in steps of 90° as shown, with the 15 magnetization state gradually changing in the magnetic poles 11 through 13 in the stator 3. Here, the respective drawings of FIGs. 3A through 3E show that the current flows through the first coil 4 and the rotor 2 is located in a position where the rotation of 20 90° is completed. As shown in FIGs. 3A through 3E, when the coil 4 is magnetically excited by the current supplied from the current control circuit 25 and the rotor 2 starts rotating in a clockwise direction as shown in FIG. 3B from the halting state of the rotor 2 25 shown in FIG. 3A, the step motor 1 is capable of starting the rotation with relatively less power consumption, because the third magnetic pole 13 is arranged close to the surface of the rotor 2. This enables the rotor 2 to be rotated for purposes of 30 saving energy. Here, the example shown in FIGs. 3A through 3E exhibits a remarkable advantage that the rotor 2 can be rotated in steps of 90° in a clockwise direction with the second coil 5 being in a halting state.

35 Further, FIGs. 4A through 4E show the above-mentioned second current supply pattern, and also show a case where only the second coil 5 is magnetically

excited in a one-phase magnetically excited state to rotate the rotor 2 in a counterclockwise direction at a step angle of 90°. FIGs. 4A through 4E show accurately reverse operations of those in FIGs. 3A through 3E.

5 That is to say, in FIG. 4A, there is no current flowing through the coils 4 and 5. In FIG. 4B through FIG. 4E, the current is controlled to supply to the coil 5 to rotate the rotor 2 in a counterclockwise direction in a time-series manner. In FIGs. 4A through 4E, the

10 polarity of the second magnetic pole 12 is reversed by reversing the current supplied to the second coil 5. Then, the polarity of the third magnetic pole 13 is opposite of that of the second magnetic pole 12. In addition, the first magnetic pole 11 is not

15 magnetically excited from the coil, and has the same polarity as that of the third magnetic pole 13.

The rotor 2 rotates in a counterclockwise direction in steps of 90° as also shown in FIGs. 4A through 4E, with the magnetization state gradually changing in the magnetic poles 11 through 13 in the stator 3. Also, the third magnetic pole 13 is arranged close to the surface of the rotor 2 when the rotor 2 starts rotating in a counterclockwise direction. This makes it possible to start the rotation at a relatively 25 small torque and suppress the power consumption. FIGs. 4A through 4E show a case where the rotor 2 can be rotated in a counterclockwise direction in steps of 90° with the first coil 4 being in a halting state.

FIG. 5 is a view showing a stator having a preferable shape suitable for use in the step motor 1. In FIG. 5, the same components and configurations as those of FIG. 1 and FIGs. 2A through 2E have the same reference numerals. The first magnetic pole 11 and the second magnetic pole 12 of the stator 3 are configured 35 to face the circumferential surface of the rotor, not shown, and to be formed into a shape having a vertically longer side to correspond to the longer side

of the rotor. The stator 3 includes arms 31 and 32 on both sides, and the arms 31 and 32 are connected to a base 35. The third magnetic pole 13 is formed in the center of the base 35. The third magnetic pole 13 is 5 also formed to have a shape having a vertically longer side, same as those of the first magnetic pole 11 and the second magnetic pole 12. The magnetic poles 11 through 13 are formed to have such a vertically longer side and extend in both directions of thickness of the 10 stator 3. In addition, the shape having a vertically longer side may be formed by extending in either direction of thickness, although the length becomes the half.

The stator 3 includes the arms 31 and 32, around 15 which the coils 4 and 5 are wound for magnetically exciting the first through third magnetic poles. To position the coils 4 and 5, projections 33 and 34 are provided on back ends of the arms. Such provided projections 33 and 34 are capable of realizing the 20 structure, in which the coils 4 and 5 respectively wound around the arms 31 and 32 can be surely positioned. In addition, indentations 37 through 39 are formed on tops of the magnetic poles 11 through 13. The step motor 1 in accordance with the present 25 embodiment is incorporated into a module together with upper and lower cases. The indentations 37 through 39 are for use in positioning the case to be set.

FIG. 6 is a perspective view showing an 30 appearance of the step motor 1, which is incorporated into a module with main components thereof. Also in FIG. 6, the same components and configurations as those of FIG. 1 and FIGs. 2A through 2E have the same reference numerals. FIG. 6 shows a module in which an upper case 7 and a lower case 8 are set together with 35 the main components from top and bottom. Such step motor module is employed for a shutter driving portion of a camera, enabling the step motor that consumes less

power at the time of activation. It is possible to set the step angle at 45° , 90° , 135° , 180° , and more, by controlling the current with the current control circuit 25. This makes it possible to provide the step 5 motor with high flexibility, in which the step angle is adjustable.

The afore-mentioned rotor may have a shape of cylinder; a stator having a plan view of substantially lateral U-shape is arranged to face a circumferential 10 surface of the rotor; the first magnetic pole and the second magnetic pole are provided on both ends of the stator; and the third magnetic pole is provided in the center of the stator. In addition, preferably, in the 15 afore-mentioned step motor, the first coil is provided between the first magnetic pole and the third magnetic pole and the second coil is provided between the second magnetic pole and the third magnetic pole; and the stator includes protrusions for preventing displacement of the first coil and the second coil. With such 20 protrusions, the positions of the first coil and the second coil are stable, and it is possible to provide the step motor having a more preferable structure.

Additionally, the first coil and the second coil 25 are connected to a current control circuit that magnetically excites them. It is possible to control the rotation of the stator in a two-phase magnetically excited state by changing the current directions to be applied from the current control circuit to the first coil and the second coil. Furthermore, the first coil 30 and the second coil are connected to a current control circuit that magnetically excites them. The rotation of the stator may be controlled in a one-phase magnetically excited state by changing the current direction to be applied from the current control 35 circuit to either the first coil or the second coil. When the current is supplied to magnetically excite the first coil and the second coil so as to control the

drive of the rotor, the rotor may be rotated at a rotor step angle of 45° . Also, when the current is supplied to magnetically excite either the first coil or the second coil so as to control the drive of the rotor,
5 the rotor may be rotated at a rotor step angle of 90° . Accordingly, it is possible to provide the step motor with high flexibility, because the step angle can be changed as described.

Advantageous Effect of the Invention

10 According to the present invention, it is possible to intensify the influence, on a rotor having four magnetic poles, of the magnetic field set up from a third magnetic pole provided on a stator. This makes it possible to relatively weaken the magnetic fields
15 set up from the first magnetic pole and the second magnetic pole, which intend to intensify the influence on the rotor, and provide a step motor by which a rotor detent torque is small and power consumption is suppressed.

20 The present invention is not limited to the above-mentioned embodiments, and other embodiments, variations and modifications may be made without departing from the scope of the present invention.